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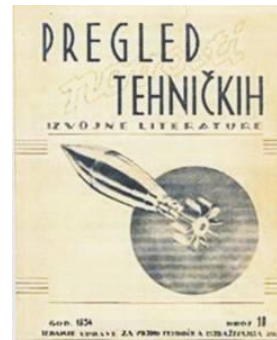
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[2] MULER,A.: *Internal Preload Control of Redundantly Actuated Parallel Manipulators-Its Application to Backlash Avoiding Control*, IEEE Transaction on Robotics, August 2005, Vol.21, No.4, pp.668-677.

Reference to a book:

[3] CHALLA,S., EVANS,R., MORELANDE,M., MUŠICKI,D.: *Fundamentals of Object Tracking*, Cambridge University Press, 2011.

Reference to a website:

[4] Statistics and Machine Learning Toolbox User's Guide, Matwork Inc., https://www.mathworks.com/help/pdf_doc/stats.pdf, Data of last access: 04/28/2018, 2017.

Reference to a conference proceedings and papers:

[5] LOLOEL,A.Z., AREF,M.M., TAGHIRAD,H.D.: *Wrench Feasible Workspace Analysis of Cable-Driven Parallel Manipulators Using LMI Approach*, International Conference on Advanced Intelligent Mechatronics, Suntec Convention and Exhibition Center, Singapore, July 14/17, 2009, pp. 1034-1039.

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