Scientific Technical Review



Guide for authors

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Articles should be original scientific or professional contributions reporting a complete research work leading to the understanding and application of knowledge based on theoretical, experimental or computational approaches. Papers combining theory and experiments or combining basic and applied research are very welcome.

The Journal anchorages papers from young researchers.

Contributions are invited in all areas pertaining to:

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- Mechanics
- Computer technology
- Telecommunication and information technologies
- Materials and chemical technologies
- Mechatronics
- Automation and control engineering

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All manuscripts must contain the essential elements needed to convey the manuscript: Title, Author names and affiliations, Corresponding author, Abstract, Keywords, Main text and References.

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Authors name and affiliations. Clearly indicate the given name(s) and family name(s) of each author. Present the author's affiliation addresses below the names. Provide the full postal address of each affiliation, including the country name and e-mail address of each author. Clearly indicate corresponding author.

Abstract and Keywords. A concise and factual abstract not exceeding 150 words in length is required. Formulas should be avoided within the abstract. Immediately after the abstract, provide a maximum 6 keywords.

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There are no strict requirements on reference formatting at submission. Reference can be in any style or format as long as the style is consistent. Where applicable, author(s) name(s), journal title/book title, chapter title/article title, year of publication, volume number/book chapter and the article number or pagination must be presented. Use of DOI is highly encouraged. If you use reference management software, please use one of the standard styles of referencing.

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- [1] MANDIĆ, S.: Guidance of Ground to Ground Rockets Using Flight Path Steering Method, Scientific Technical Review, ISSN 1820-0206, 2009, Vol.89, No.3-4, pp. 3-11.
- [2] MULER, A.: Internal Preload Control of Redundantly Actuated Parallel Manipulators-Its Application to Backlash Avoiding Control, IEEE Transaction on Robotics, August 2005, Vol.21, No 4, pp. 668-677.

Reference to a book:

[3] CHALLA, S., EVANS, R., MORELANDE, M., MUŠICKI, D.: Fundamentals of Object Tracking, Cambridge University Press, 2011.

Reference to a website:

[4] Statistics and Machine Learning Toolbox User's Guide, Matwork Inc., https://www.mathworks.com/help/pdf doc/stats.pdf, Data of last access: 04/28/2018, 2017.

Reference to a conference proceedings and papers:

[5] LOLOEI, A.Z., AREF, M.M., TAGHIRAD, H.D.: Wrench Feasible Workspace Analysis of Cable-Driven Parallel Manipulators Using LMI Approach, International Conference on Advanced Intelligent Mechatronics, Suntec Convention and Exhibition Center, Singapore, July 14/17, 2009, pp. 1034-1039.

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Please list the names and contact details of minimum 2 reviewers who are expert in the topic that your paper covers.

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